

The Multisymplectic Form Formula for Lagrangian PDEs

Mats Vermeeren



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Lagrangian Mechanics

Setup:

- ▶ Configuration space Q – coordinates (q^1, \dots, q^N) .
- ▶ Phase space TQ – coordinates $(q^1, \dots, q^N, \dot{q}^1, \dots, \dot{q}^N)$.
- ▶ Lagrange function $L : TQ \rightarrow \mathbb{R}$.
- ▶ Solutions curves $q : [a, b] \rightarrow Q : t \mapsto (q^1(t), \dots, q^N(t))$ are critical points of the action

$$\begin{aligned} S(\alpha) &= \int_a^b L(q^1(t), \dots, q^N(t), \dot{q}^1(t), \dots, \dot{q}^N(t)) dt \\ &= \int_a^b L(q(t), \dot{q}(t)) dt. \end{aligned}$$

If $L = (\text{kinetic energy}) - (\text{potential energy})$, this describes Newtonian mechanics.

The Euler-Lagrange Equations

Fix endpoints $q(a), q(b)$, take any variation δq of $q(t)$:

$$\begin{aligned}
 0 = \delta S &= \int_a^b \delta L(q(t), \dot{q}(t)) dt \\
 &= \int_a^b \frac{\partial L}{\partial q^i} \delta q^i + \frac{\partial L}{\partial \dot{q}^i} \delta \dot{q}^i dt \\
 &= \int_a^b \left(\frac{\partial L}{\partial q^i} \delta q^i - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}^i} \right) \delta q^i \right) dt + \frac{\partial L}{\partial \dot{q}^i} \delta q^i \Big|_{t=a}^{t=b} \\
 &= \int_a^b \left(\frac{\partial L}{\partial q^i} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}^i} \right) \right) \delta q^i dt.
 \end{aligned}$$

The Euler-Lagrange equations follow:

$$\frac{\partial L}{\partial q^i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}^i} = 0.$$

The Symplectic Form

Leave endpoints $q(a), q(b)$ free, restricts to curves $q(t)$ which solve the EL-equations:

$$\begin{aligned} \delta S &= \int_a^b \frac{\partial L}{\partial q^i} \delta q^i + \frac{\partial L}{\partial \dot{q}^i} \delta \dot{q}^i dt \\ &= \int_a^b \left(\frac{\partial L}{\partial q^i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}^i} \right) \delta q^i dt + \frac{\partial L}{\partial \dot{q}^i} \delta q^i \Big|_{t=a}^{t=b} \\ &= \frac{\partial L}{\partial \dot{q}^i} \delta q^i \Big|_{t=a}^{t=b}. \end{aligned}$$

Introduce **conjugate momenta** $p_i := \frac{\partial L}{\partial \dot{q}^i}$, then

$$\delta S = p_i \delta q^i \Big|_{t=a}^{t=b}.$$

The Symplectic Form

In terms of differentials:

$$\delta S = dS(\delta q, \delta \dot{q}) \quad \text{and} \quad \delta q^i = dq^i(\delta q, \delta \dot{q}),$$

so

$$dS = p_i dq^i \Big|_{t=a}^{t=b}.$$

Take exterior derivative:

$$0 = dp_i \wedge dq^i \Big|_{t=a}^{t=b} = dp_i(b) \wedge dq^i(b) - dp_i(a) \wedge dq^i(a).$$

The **symplectic two-form** $\omega := dp_i \wedge dq^i$ is a conserved quantity.

Lagrangian Field Theory

Setup:

- ▶ Spacetime manifold X – coordinates $(x^\mu) = (x^0, \dots, x^n)$
- ▶ Configuration space: trivial vector bundle $Y = X \times F$ – coordinates $(x^\mu, y^i) = (x^1, \dots, x^n, y^1, \dots, y^m)$.
- ▶ Phase space $J^1 Y$ – coordinates (x^μ, y^i, y_μ^i) .

Section $\phi : X \rightarrow Y$ extends to

$$J^1 \phi : X \rightarrow J^1 Y : x \mapsto (x^\mu, \phi(x)^i, \partial_\mu \phi^i(x)).$$

Example. Mechanics:

$$X = \mathbb{R} \quad - \quad \text{time}$$

$$F = Q \quad - \quad \text{configuration space}$$

$$J^1 Y = X \times TQ \quad - \quad \text{time} \times \text{phase space}$$

Euler Lagrange Equations

Setup:

- ▶ Lagrange function:

$$\mathcal{L} : J^1 Y \rightarrow \Omega^{n+1} X : (x^\mu, y^i, y_\mu^i) \mapsto L(y^i, y_\mu^i) dx_0 \wedge \dots \wedge dx_n.$$

- ▶ Action:

$$S(\phi) = \int_{U \subset X} L(\phi^i, \partial_\mu \phi^i) dx_0 \wedge \dots \wedge dx_n.$$

Form and derivation of [Euler-Lagrange equations](#)

$$\frac{\partial L}{\partial y^i} - \frac{d}{dx^\mu} \frac{\partial L}{\partial y_\mu^i} = 0$$

are very similar to mechanics.

The Multisymplectic Form Formula – MPS version

Considering the boundary terms leads to **Multisymplectic form formula**:

$$\int_{\partial U} i_{\text{something}} i_{\text{something similar}} (j^1\phi)^*\omega = 0,$$

where

- ▶ i denotes the interior product and $*$ the pull-back.
- ▶ $\phi : U \rightarrow J^1Y$ is any solution of the EL equations.
- ▶ ω is the **Multisymplectic $(n+2)$ -form**:

$$\omega = d \left(\frac{\partial L}{\partial y_\mu^i} dy^i \wedge d^n x_\mu + \left(L - \frac{\partial L}{\partial y_\mu^i} y_\mu^i \right) d^{n+1}x \right),$$

where $d^{n+1}x = dx^0 \wedge \dots \wedge dx^n$,

and $d^n x_\mu = (-1)^\mu dx^0 \wedge \dots \wedge \widehat{dx^\mu} \wedge \dots \wedge dx^n$.

- ▶ “something” is a first variation of ϕ (extended to J^1Y).

Horizontal and Vertical One-Forms

- ▶ Phase space $J^\infty Y$ – coordinates $(x^\mu, y^i, y_\mu^i, y_{\mu\nu}^i, \dots, y_{\mathcal{I}}^i, \dots)$.

Section $\phi : X \rightarrow Y$ extends to

$$j^\infty \phi : X \rightarrow J^\infty Y : x \mapsto (x^\mu, \phi(x)^i, \partial_\mu \phi^i(x), \partial_{\mu\nu} \phi^i(x), \dots).$$

- ▶ Horizontal one-forms

$$\mathcal{H} = \text{span}\{dx^0, \dots, dx^n\}$$

annihilate vertical vector fields.

- ▶ Vertical one-forms

$$\mathcal{V} = \text{span}\{dy^i - y_\mu^i dx^\mu, dy_\nu^i - y_{\nu\mu}^i dx^\mu, \dots, y_{\mathcal{I}}^i - y_{\mathcal{I}\mu}^i dx^\mu, \dots\}$$

annihilate extended vector fields.

Type (h,v) -Forms

- ▶ Type (h,v) -forms on $J^\infty Y$

$$\Omega^{h,v}(J^\infty Y) = \text{span}\{\alpha^1 \wedge \dots \wedge \alpha^h \wedge \beta^1 \wedge \dots \wedge \beta^v \mid \alpha^j \in \mathcal{H}, \beta^j \in \mathcal{V}\} \\ \subset \Omega^{h+v}(J^\infty Y)$$

- ▶ Exterior derivative $d : \Omega^k \rightarrow \Omega^{k+1}$ splits uniquely into

$$d_{\mathcal{H}} : \Omega^{h,v} \rightarrow \Omega^{h+1,v} \quad \text{and} \quad d_{\mathcal{V}} : \Omega^{h,v} \rightarrow \Omega^{h,v+1}$$

such that

$$d = d_{\mathcal{H}} + d_{\mathcal{V}}.$$

The Variational Bicomplex

The variational bicomplex on $J^\infty Y$:

$$\begin{array}{ccccccc}
 \vdots & & \vdots & & \vdots & & \vdots \\
 \uparrow d_{\mathcal{V}} & & \uparrow d_{\mathcal{V}} & & \uparrow d_{\mathcal{V}} & & \uparrow d_{\mathcal{V}} \\
 \Omega^{0,2} & \xrightarrow{d_{\mathcal{H}}} & \Omega^{1,2} & \xrightarrow{d_{\mathcal{H}}} & \dots & \xrightarrow{d_{\mathcal{H}}} & \Omega^{n,2} & \xrightarrow{d_{\mathcal{H}}} & \Omega^{n+1,2} & \xrightarrow{d_{\mathcal{H}}} & 0 \\
 \uparrow d_{\mathcal{V}} & & \uparrow d_{\mathcal{V}} & & \uparrow d_{\mathcal{V}} & & \uparrow d_{\mathcal{V}} & & \uparrow d_{\mathcal{V}} & & \\
 \Omega^{0,1} & \xrightarrow{d_{\mathcal{H}}} & \Omega^{1,1} & \xrightarrow{d_{\mathcal{H}}} & \dots & \xrightarrow{d_{\mathcal{H}}} & \Omega^{n,1} & \xrightarrow{d_{\mathcal{H}}} & \Omega^{n+1,1} & \xrightarrow{d_{\mathcal{H}}} & 0 \\
 \uparrow d_{\mathcal{V}} & & \uparrow d_{\mathcal{V}} & & \uparrow d_{\mathcal{V}} & & \uparrow d_{\mathcal{V}} & & \uparrow d_{\mathcal{V}} & & \\
 \Omega^{0,0} & \xrightarrow{d_{\mathcal{H}}} & \Omega^{1,0} & \xrightarrow{d_{\mathcal{H}}} & \dots & \xrightarrow{d_{\mathcal{H}}} & \Omega^{n,0} & \xrightarrow{d_{\mathcal{H}}} & \Omega^{n+1,0} & \xrightarrow{d_{\mathcal{H}}} & 0
 \end{array}$$

A “vertical” extension of the de Rham complex on X :

$$\Omega^0(X) \xrightarrow{d_X} \Omega^1(X) \xrightarrow{d_X} \dots \xrightarrow{d_X} \Omega^n(X) \xrightarrow{d_X} \Omega^{n+1}(X) \xrightarrow{d_X} 0$$

Integration of Type (h, v) -Forms

Setup:

- ▶ $\alpha \wedge \beta \in \Omega^{h, v}(J^\infty Y)$, with

$$\alpha \in \Omega^{h, 0}(J^\infty Y) = \Omega^h(X) \quad \text{and} \quad \beta \in \Omega^{0, v}(J^\infty Y)$$

- ▶ M – an h -dimensional submanifold of the base manifold X .
- ▶ $J^\infty Y$ is locally trivial: $J^\infty Y = X \times F^\infty Y$.
- ▶ $\Lambda^v(F^\infty Y)$ – the space of anti-symmetric v -tensors on $F^\infty Y$.
- ▶ An (h, v) -form can be seen as a $\Lambda^v(F^\infty Y)$ -valued h -form on X .

The **integral of an (h, v) -form** on M is an anti-symmetric v -tensor on $F^\infty Y$:

$$\left(\int_M \alpha \wedge \beta \right) (W_1, \dots, W_v) = \int_M \underbrace{\beta(W_1, \dots, W_v)}_{\in \mathbb{R}} \underbrace{\alpha}_{\in \Omega^{h, 0}}.$$

The Multisymplectic Form Formula – Take 2

- ▶ Volume element $d^n V$ on ∂U .
- ▶ n_μ coordinates of the unit normal vector to ∂U .
- ▶ Normal momenta:

$$\pi_i = \frac{\partial L}{\partial y_\mu^i} n_\mu.$$

(Compare conjugate momenta in mechanics: $p^i = \frac{\partial L}{\partial \dot{q}^i}$.)

Considering the boundary terms yields

Theorem (Multisymplectic Form Formula)

$$\int_{\partial U} d_\gamma \pi_i \wedge d_\gamma y^i \wedge d^n V = 0.$$

The Multisymplectic Form Formula – Take 2

Proof. Along solutions of the Euler-Lagrange equations we have:

$$\begin{aligned}
 \delta S &= \int_U \left(\frac{\partial L}{\partial y^i} \delta y^i + \frac{d}{dx^\mu} \frac{\partial L}{\partial y_\mu^i} \delta y_\mu^i \right) d^{n+1}x \\
 &= \int_U \left(\frac{\partial L}{\partial y^i} - \frac{d}{dx^\mu} \frac{\partial L}{\partial y_\mu^i} \right) \delta y^i d^{n+1}x + \int_{\partial U} \left(\frac{\partial L}{\partial y_\mu^i} \delta y^i \right) d^n x_\mu \\
 &= \int_{\partial U} \left(\frac{\partial L}{\partial y_\mu^i} \delta y^i \right) d^n x_\mu \\
 \Rightarrow dS &= \int_{\partial U} \frac{\partial L}{\partial y_\mu^i} d_{\mathcal{Y}} y^i \wedge d^n x_\mu = \int_{\partial U} \pi_i d_{\mathcal{Y}} y^i \wedge d^n V.
 \end{aligned}$$

Take the exterior derivative again:

$$0 = \int_{\partial U} d_{\mathcal{Y}} \pi_i \wedge d_{\mathcal{Y}} y^i \wedge d^n V.$$

